## ACTUATOR LA36

## Features:

- 12, 24 or 36 V DC Permanent magnetic motor
- Thrust from $500 \mathrm{~N}-10.000 \mathrm{~N}$ depending on gear ratio and spindle pitch
- 10.000 N actuator cannot be ordered without electrical endstop
- 10.000 N actuator can be ordered in push and pull
- Max. speed up to $160 \mathrm{~mm} / \mathrm{sec}$. depending on load and spindle pitch
- Heavy duty aluminium housing for harsh conditions
- Highly efficient acme thread spindle
- Protection class: IP66 for outdoor use (dynamic), furthermore the actuator can be washed down by a high pressure cleaner (IP69K - static)
- Hand crank for manual operation
- Mechanical overload protection through integrated slip clutch (adjusted to 1.2-1.5 times max. load)
- Integrated brake, high self-lock ability
- End play - 2 mm max.
- Non rotating piston rod eye
- Back fixture turnable in steps of 30 degrees
- Noise level: 73 dB (A) measuring method DSIEN ISO 8746 actuator not loaded


## Options:

- Built in end stop switches
- Adjustable magnetic sensors for end stop signals (code no. 1017031)
- Hall effect sensor with $A / B$-signal
- Potentiometer full scale at 333 mm stroke with 8 mm pitch, 500 mm stroke with 12 mm pitch and 833 mm with 20 mm pitch
- Analog feedback for precise positioning
- Different back fixtures and piston rod eyes
- Exchangeable cables in different lengths
- Resetable thermal overload protection


## Usage:

- Duty cycle at max. load 20\% (up to 600 mm stroke, for strokes between 601-999 mm the max. duty cycle is $15 \%$ ) at ambient temperature $25^{\circ} \mathrm{C}$ N.B. $10.000 \mathrm{~N} 5 \%$ duty cycle.
- Ambient operating temperature $-30^{\circ} \mathrm{C}$ to $+65^{\circ} \mathrm{C}$ full performance from 5-40 ${ }^{\circ} \mathrm{C}$

TECHLINE


Technical specifications
LA36 with 12V motor

| Order number | Push max. <br> (N) | Pull max. <br> (N) | *Self-lock min. (N) Push | *Self-lock min. (N) Pull | Pitch ( $\mathrm{mm} / \mathrm{spindle}$ rev.) | Typical speed ( $\mathrm{mm} / \mathrm{s}$ ) Load |  | Standard stroke lengths (mm) In steps of 50 mm | Typical amp. <br> (A) <br> 12 V |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  |  |  |  |  |  | no | full |  | No load | Full load |
| 362CXXXXXXXXXAXX | 10000 | 10000 | 13000 | 13000 | 8 | 11 | 7 | 100-999* | 4.5 | 22 |
| 363AXXXXXXXXAXX | 2600 | 2600 | 3400 | 3400 | 12 | 40.7 | 30.6 | 100-999 | 4.5 | 21 |
| 363BXXXXXXXXXAXX | 4500 | 4500 | 5800 | 5800 | 12 | 23.1 | 17.8 | 100-999* | 4.5 | 20.7 |
| 363CXXXXXXXXXAXX | 6800 | 6800 | 8800 | 8800 | 12 | 15.5 | 11.9 | 100-999* | 4.5 | 21 |
| 365AXXXXXXXXAXX | 1700 | 1700 | 2200 | 2200 | 20 | 68 | 52 | 100-999 | 4.5 | 22 |
| 365FXXXXXXXXAXX | 500** | 500** | 1000 | 1000 | 20 | 160 | 135 | 100-999 | 4.5 | 20 |

LA36 with 24V motor

| Order number | Push max. <br> ( N ) | Pull max. <br> (N) | *Self-lock min. (N) Push | *Self-lock min. (N) Pull | Pitch ( $\mathrm{mm} / \mathrm{spindle} \mathrm{rev}$.) | $\begin{aligned} & \text { Typical speed } \\ & (\mathrm{mm} / \mathrm{s}) \\ & \text { Load } \end{aligned}$ |  | Standard stroke lengths (mm) In steps of 50 mm | Typical amp. <br> (A) <br> 24 V |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  |  |  |  |  |  | no | full |  | No load | Full load |
| 362CXXXXXXXXXBXX | 10000 | 10000 | 13000 | 13000 | 8 | 11 | 7 | 100-999* | 2.4 | 10.4 |
| 363AXXXXXXXXXBXX | 2600 | 2600 | 3400 | 3400 | 12 | 41 | 32.3 | 100-999 | 2.4 | 10.4 |
| 363BXXXXXXXXXBXX | 4500 | 4500 | 5800 | 5800 | 12 | 23.3 | 18.9 | 100-999* | 2.4 | 10.2 |
| 363CXXXXXXXXXBXX | 6800 | 6800 | 8800 | 8800 | 12 | 15.7 | 12.7 | 100-999* | 2.4 | 10.3 |
| 365AXXXXXXXXXBXX | 1700 | 1700 | 2200 | 2200 | 20 | 68 | 52 | 100-999 | 2.4 | 10.3 |
| 365FXXXXXXXXBXX | 500** | 500** | 1000 | 1000 | 20 | 160 | 135 | 100-999 | 2.4 | 10.0 |

LA36 with 36V motor

| Order number | Push max. <br> ( N ) | Pull max. <br> (N) | *Self-lock <br> min. (N) Push | *Self-lock min. (N) Pull | Pitch ( $\mathrm{mm} / \mathrm{spindle}$ rev.) | $\begin{aligned} & \text { Typical speed } \\ & (\mathrm{mm} / \mathrm{s}) \\ & \text { Load } \end{aligned}$ |  | Standard stroke lengths (mm) In steps of 50 mm | Typical amp. <br> (A) <br> 36 V |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  |  |  |  |  |  | no | full |  | No load | Full load |
| 362CXXXXXXXXCXX | 10000 | 10000 | 13000 | 13000 | 8 | 11 | 7 | 100-999* | 2.0 | 8.0 |
| 363AXXXXXXXXCXX | 2600 | 2600 | 3400 | 3400 | 12 | 41 | 33.5 | 100-999 | 2.0 | 8.0 |
| 363BXXXXXXXXCXX | 4500 | 4500 | 5800 | 5800 | 12 | 23.3 | 19.1 | 100-999* | 2.0 | 8.0 |
| 363CXXXXXXXXCXX | 6800 | 6800 | 8800 | 8800 | 12 | 15.7 | 12.8 | 100-999* | 2.0 | 8.0 |
| 365AXXXXXXXXCXX | 1700 | 1700 | 2200 | 2200 | 20 | 68 | 52 | 100-999 | 2.0 | 8.0 |
| 365FXXXXXXXXCXX | 500** | 500** | 1000 | 1000 | 20 | 160 | 135 | 100-999 | 2.0 | 8.0 |

* There are limitations on the stroke length if you need full load, please see " LA36 Load v. Stroke Length"
** Note: Fully loaded actuators need a softstart in order to prevent the clutch slipping at start (see curves).
Speed and current curves:


10.000 N not tested


* Speed and current based on nominal power supply of 12, 24, 36VDC.

LA36
Ordering example:


NB: When ordering AISI piston rod eye and back fixture, stainless steel screws are automatically included. When ordering standard stroke length with end-stop $1,2,3,4$ or 5 the stroke length will be $3-4 \mathrm{~mm}$ shorter.

## LA36 dimensions:



## I/O specifications: Power supply - Motor

| Item | Specification | Comment |
| :--- | :--- | :--- |
| Power supply |  | Cable dimension: $2 \times 2.5 \mathrm{~mm}^{2}$ <br> $(2 \times$ AWG14) for all different voltages. |
| Input voltage | $12 \mathrm{VDC}, \pm 20 \%$ <br> $24 \mathrm{VDC}, \pm 10 \%$ <br> $36 \mathrm{VDC}, \pm 10 \%$ | Ambient temperature $25^{\circ} \mathrm{C}$ |
| Duty cycle | $20 \%$ at max. load | Actuator direction can be controlled with a double-throw switch <br> with the middle position "off" |
| Current consumption | $2-22$ Amp. depending on load and voltage (see graphs) | To extend actuator: <br> Connect Brown to positive <br> Connect Blue to negative <br> To retract actuator: <br> Connect Brown to negative <br> Connect Blue to positive |

Note: Please note on varients with fast gear (500N-LA365F), it is necessary to use soft start to avoid the actuator clutch slipping when started.

Positioning feedback - Potentiometer

| Item | Specification | Comment |
| :---: | :---: | :---: |
| Absolute positioning |  |  |
| Potentiometer | Bourns 0-10 K ohm A 5\%, 10-Turn | Type: 3540 Wirewound |
| Output range with 8 mm spindle pitch | 0 K ohm $=0 \mathrm{~mm}$ stroke $10 \mathrm{~K} \mathrm{ohm}=333 \mathrm{~mm}$ stroke | The same for all LA36 8 mm models e.g. 166.6 mm stroke $=5 \mathrm{Kohm}$ |
| Output range with 12 mm spindle pitch | 0 K ohm $=0 \mathrm{~mm}$ stroke $10 \mathrm{~K} \mathrm{ohm}=500 \mathrm{~mm}$ stroke | The same for all LA36 12 mm models e.g. 250 mm stroke $=5 \mathrm{Kohm}$ |
| Output range with 20 mm spindle pitch | 0 K ohm $=0 \mathrm{~mm}$ stroke 10 K ohm $=833 \mathrm{~mm}$ stroke | The same for all LA36 20 mm models e.g. 416.5 mm stroke $=5 \mathrm{Kohm}$ |
| Linearity | $\pm 0.25 \%$ |  |
| Output protection | 1 Kohm protection resistor |  |
| Connection | Common - = Black <br> +10 V exitation $=$ White <br> $0=10 \mathrm{~V}$ out $=$ Violet | +10 V or other value |

Note: Please note that Potentiometer is not possible on varients with fast gear (LA365F) -500N.

Positioning feedback - Hall sensors.

| Item | Specification | Comment |
| :---: | :---: | :---: |
| Relative positioning |  |  |
| Signal description | Can be used for both direction and positioning |  |
| Input Voltage | 12-36V DC | Cable dimension: $6 \times 0.5 \mathrm{~mm}^{2}(6 \times$ AWG20) for all different voltages |
| Output voltage | Always the same as input voltage <br> Note: max. output voltage 24V DC $\begin{aligned} & 12 \mathrm{~V}: 11 \mathrm{~V} \pm 1 \mathrm{~V} \\ & 24 \mathrm{~V}: 23 \mathrm{~V} \pm 1 \mathrm{~V} \\ & 36 \mathrm{~V}: 23 \mathrm{~V} \pm 1 \mathrm{~V} \end{aligned}$ |  |
| Resolution <br> (Distance the piston rod moves per count) | LA362C: Actuator $=0.1 \mathrm{~mm}$ per count. <br> LA363C: Actuator $=0.2 \mathrm{~mm}$ per count. <br> LA363B: Actuator $=0.3 \mathrm{~mm}$ per count. <br> LA363A: Actuator $=0.4 \mathrm{~mm}$ per count. <br> LA365A: Actuator $=0.7 \mathrm{~mm}$ per count <br> Movement per single Hall pulse: <br> LA362C Actuator $=0.4 \mathrm{~mm}$ per pulse <br> LA363C Actuator $=0.7 \mathrm{~mm}$ per pulse <br> LA363B Actuator $=1.0 \mathrm{~mm}$ per pulse <br> LA363A Actuator $=1.7 \mathrm{~mm}$ per pulse <br> LA365A Actuator $=2.9 \mathrm{~mm}$ per pulse | The Hall sensor signals are generated by the turning of the actuator gearing. <br> These signals can be fed into a PLC (Programmable Logic Controller). In the PLC the quadrature signals (fig. 1) can be used to register the direction and position of the piston rod. <br> N.B. For more precise measurements, please contact LINAK. |
| Frequency | Frequency is $14-26 \mathrm{~Hz}$ on $A$ signal (and the same on $B$ signal) depending on load. <br> Every pulse is "ON" for 10 ms <br> There is a phase shift of $90^{\circ} \pm 30^{\circ}$ between the phases | Low frequency with a high load Higher frequency with no load |
| Current consumption | 15 mA | Also when actuator is not running |
| Switching capacity | 40 mA , max. pr. channel | Max. 680 nF |
| Connection | Supply = Red <br> Hall A = Yellow <br> Hall $B=$ Green <br> Common - = Black |  |
| Diagram: |  | ts direction <br> ition. <br> Fig. 1 |

## I/O Specification: Analog feedback

| Item | Specification | Comment |
| :---: | :---: | :---: |
| Description | The actuator can be equipped with electronic circuit that gives an analog feedback signal when the actuator moves | + |
| Input voltage | 12-36V DC | Feedback circuit to be powered 1 second before motor runs, and until 1 second after the motor has stopped. Cable dimension $6 \times 0,5 \mathrm{~mm}^{2}$ $\text { ( } 6 \times \text { AWG20) }$ |
| Output voltage | 0-10 V <br> OV = Fully retracted <br> $10 \mathrm{~V}=$ Fully extended <br> 0,5-4,5V (Option C) <br> $0,5 \mathrm{~V}=$ Fully retracted <br> $4,5 \mathrm{~V}=$ Fully extended | +/-0.3 V |
| Current consumption | Max. 40 mA | Also when actuator is not running |
| Connection | Supply: White (Pin 3) (+12V to 36V) Ground: Black (Pin 1) <br> Signal: Violet (Pin 4) (0-10V Out) | Use cable 0367003-XXXX |
| Combinations | The Absolute positioning shall be combined with limit switches. Can be combined with ends stop signal | $36 x x x x x 1$ Bxxxxxx/36xxxxx1Cxxxxxx $36 x x x x x 2 \mathrm{Bxxxxxx} / 36 x x x x x 2 \mathrm{Cxxxxxx}$ |

Note: It is recommendable to have the actuator to activate its limit switches on a regular basis. End stop signal: max 20 mA available.
End stop signal: max 20 mA available
O Specification: PLC option
For more details contact LINAK

## LA36 Piston Rod Eye

Option "0"
LINAK P/N: 0361016


SECTION A-A

Option "2"
LINAK P/N: 0361109


Option "A"
LINAK P/N: 0361260


Option
LINAK P/N:

Option "1"
LINAK P/N: 0361018

$\varnothing 12.9 \pm 0.1$


Option "3"
LINAK P/N: 0361224


Option "B"
LINAK P/N: 0361275


Option
LINAK P/N:

Option "4" LINAK P/N: 0361135

LINAK P/N: 0361138


Option "D" LINAK P/N: 0361292


Option "C" LINAK P/N: 0361285



LA36 Load versus Stroke Length


- For applications that only operate in pull the limitations are 999 mm stroke and $10,000 \mathrm{~N}$ load.
- The Piston Rod Eye is only allowed to turn 0-90 degrees
- Safety factor 2


## Manual hand crank

The manual hand crank can be used in the case of power failure.

The cover over the Allen Key socket must be unscrewed before the Allen Key can be inserted and the Hand Crank operated.

Hand Crank Torque: Max. 16 Nm (at maximum load)
Piston Rod movement per turn
Gear $A=10.5 \mathrm{~mm}$
Gear $B=6.0 \mathrm{~mm}$
Gear $C=4.0 \mathrm{~mm}$
Gear $F=27 \mathrm{~mm}$


Note:

- The power supply has to be disconnected during manual operation.
- If the actuator is operated as a Hand crank, it must be operated by hand or carefully by machine, otherwise there is a potential risk of overloading and hereby damaging the actuator. LA36 with CS or MODBUS options only operate by hand.
- With stainless steel screws: 5 mm Allen Key

The LA36 is tested according to the following standards:

| Test | Specification: | Comment |
| :---: | :---: | :---: |
| Cold test | $\begin{aligned} & \text { EN60068-2-1 (Ab) } \\ & \text { EN60068-2-1 (Ad) } \end{aligned}$ | Storage at low temperature: $-40^{\circ} \mathrm{C}$ Operating at low temperature: $-30^{\circ} \mathrm{C}$ |
| Dry heat | $\begin{aligned} & \text { EN60068-2-2 (Bb) } \\ & \text { EN60068-2-2 (Bd) } \end{aligned}$ | Storage at high temperature: $+90^{\circ} \mathrm{C}$ Operating at high temperature: $+60^{\circ} \mathrm{C}$ |
| Change of temperature | EN60068-2-14 (Na) | Rapid change in temperature: $+100^{\circ} \mathrm{C}$ to $-30^{\circ} \mathrm{C}$ |
| Damp heat | EN60068-2-30 (Db) <br> EN60068-2-3 (Ca) | Damp heat, Cyclic: Relative humidity 93-98 \% High $+55^{\circ} \mathrm{C}$, low $+25^{\circ} \mathrm{C}$ <br> Damp heat, Steady: Relative humidity 93-95 \% $+40^{\circ} \mathrm{C} \pm 2^{\circ} \mathrm{C}$ |
| Salt spray | EN60068-2-52 (Kb) | Salt spray test: 500 hours incl. spraying periods + humidity storage |
| Degrees of protection | EN60529-IP66 | IP6X - Dust: Dust-tight <br> IPX6 - Water: No ingress of water causing damage |
| Chemicals | BS7691/96 hours | Resistant against: diesel, hydraulic oil, ethylene glycol, urea nitrogen, liquid lime, NPK fertilizers |
| Free fall |  | Free fall from all sides: 0.4 meters on to steel |
| Vibration | EN60068-2-36 (Fdb) <br> EN60068-2-6 (Fc) | $\begin{array}{ll} \hline \text { Random vibration: } & \text { Short time } 6.29 \mathrm{~g} \mathrm{RMS} \text { (Rod Mean Square) } \\ & \text { Long time } 7.21 \mathrm{~g} \mathrm{RMS} \\ \text { Sinus vibration: } & \text { Freq. } 5-25 \mathrm{~Hz} \text {, amplitude }=3.3 \mathrm{~mm} \mathrm{pp} \\ & \text { Freq. } 25-200 \mathrm{~Hz} \text {, acceleration } 4 \mathrm{~g} \end{array}$ |
| Bump | EN60068-2-29 (Eb) | Bump test: Level 40 g for 6 milliseconds. 3,000 bumps |
| Shock | EN60068-2-27 (Ea) | Shock test: Level 100 g for 6 milliseconds |
| Power supply | ASAE EP455 (1990) | Operating voltages: $+10 \mathrm{~V}-+16 \mathrm{~V}$ Over voltage $+26(\mathrm{~V}) / 5 \mathrm{~min}$ |
| HF-immunity | EN61000-6-2 | Level: $30 \mathrm{~V} / \mathrm{m}$. at $26 \mathrm{MHz}-1000 \mathrm{MHz} ; 80 \% 1 \mathrm{KHz}$ |
| Emission | EN61000-6-4 | All levels are well within the norms of the emission standards |
| Insulation test |  | Level: $500 \mathrm{~V} \mathrm{AC/25-100} \mathrm{~Hz} \mathrm{for} 1$ minute |
| Automotive transients | ISO 7637 | Load dump test only accepted on motor power connection |

